Volatility v Trend Risk

A technical note on estimating and forecasting with the random walk with drift

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This note discusses the technical aspects of the blog Volatility v Trend Risk on forecasting and simulating sample paths with the random walk with drift.



Figure 1: Fitted κ values in the Lee-Carter model for US male mortality

Suppose we have a time series $\kappa_1, \ldots, \kappa_n$; such a time series is shown in Figure 1. The random walk with drift model is

$$\kappa_j = \kappa_{j-1} + a + \varepsilon_j, \quad \varepsilon_j \sim \mathcal{N}(0, \sigma^2), \quad j = 2, \dots, n,$$
(1)

where the ε_j are independent. The drift and volatility parameters a and σ are to be estimated from our data. We write expression (1) in terms of $y_j = \kappa_j - \kappa_{j-1}$:

$$y_j = a + \varepsilon_j, \quad \varepsilon_j \sim \mathcal{N}(0, \sigma^2), \quad j = 2, \dots, n$$
 (2)

and since y_2, \ldots, y_n are independent and identically distributed we immediately have

$$\hat{a} = \bar{y} = \frac{1}{n-1} \sum_{j=1}^{n} y_j, \quad \hat{\sigma}^2 = \frac{1}{n-2} \sum_{j=1}^{n} (y_j - \bar{y})^2.$$
 (3)

The variance and standard error of \hat{a} are given by

$$\operatorname{Var}(\hat{a}) = \operatorname{Var}(\bar{y}) = \frac{\sigma^2}{n-1} \Rightarrow \operatorname{SE}(\hat{a}) = \frac{\hat{\sigma}}{\sqrt{n-1}}.$$
(4)



Figure 2: Fitted and forecast κ values with 95% confidence interval

A rough 95% confidence interval for a is $\hat{a} \pm 2 \times \text{SE}(\hat{a})$. Now let's consider forecasting. The *m*-step ahead central forecast is

$$\hat{\kappa}_{n+m}^c = \kappa_n + m\hat{a} \tag{5}$$

with variance

$$\operatorname{Var}(\hat{\kappa}_{n+m}^c) = m^2 \operatorname{Var}(\hat{a}) \Rightarrow \operatorname{SE}(\hat{\kappa}_{n+m}^c) = m \frac{\hat{\sigma}}{\sqrt{n-1}}$$
(6)

which leads immediately to the 95% confidence interval for the central forecast shown in Figure 2.



Figure 3: Sample paths for κ with stochastic error only

The actual forecast is subject to both parameter and stochastic uncertainty. We can get a feel for the relative importance of these components by isolating each in turn. We first discuss stochastic uncertainty. We fix the drift parameter at its estimated value of \hat{a} . Conditional on this value of a, a sample path of length s is generated by

$$\hat{\kappa}_{n+m} = \kappa_n + m\hat{a} + \sum_{j=1}^{m} \varepsilon_j, \quad m = 1, \dots, s, \quad j = 1, \dots, s$$
(7)

where the ε_j are independent $\mathcal{N}(0, \hat{\sigma}^2)$. Figure 3 shows the results of generating one hundred such paths. Notice that these sample paths are subject to mean reversion. The 95% sample envelope has been computed from 1000 sample paths for greater accuracy.



Figure 4: Sample paths for κ with parameter error only

Now let's consider parameter uncertainty. Let A be the true but unknown value of the drift parameter. Using (4) we suppose that

$$A \sim \mathcal{N}\left(\hat{a}, \frac{\hat{\sigma}^2}{n-1}\right). \tag{8}$$

We generate a future possible forecast for the mean of length s with

$$\hat{\kappa}_{n+m} = \kappa_n + mA, \quad m = 1, \dots, s.$$
(9)

The result of simulating one hundred such means is shown in Figure 4. Again, the 95% sample envelope has been computed from 1000 sample paths for greater accuracy.



Figure 5: Sample paths for κ with both stochastic and parameter error

Figure 5 shows the results of including both stochastic and parametric uncertainty. These sample paths are generated with

$$\hat{\kappa}_{n+m} = \kappa_n + mA_i + \sum_{j=1}^{m} \varepsilon_{ij}, \quad m = 1, \dots, s, \quad j = 1, \dots, s, \quad i = 1, \dots, 100.$$
 (10)

Again, the ε_{ij} are independent $\mathcal{N}(0, \hat{\sigma}^2)$ and the A_i are independently generated with (8). Once more, the 95% sample envelope has been computed from 1000 sample paths for greater accuracy.



Figure 6: Central forecast for κ with various 95% sample path envelopes

How can we compare the relative contribution of stochastic and parametric uncertainty? One way is to compute the upper and lower $2\frac{1}{2}\%$ curves in each of Figures 3, 4 and 5. We do this by calculating (pointwise) the appropriate quantiles on each set of sample paths. The result is shown in Figure 6.